

Econometrics Preliminary Exam
Agricultural and Resource Economics, UC Davis

August 14, 2017

There are **FOUR** questions. Answer each part of each question. All questions are weighted equally. Within each question, each part will receive equal weight in grading.

I. **Applied Probability** You are evaluating employees at a large firm. Each employee i performs a repeatable task multiple times and has a success rate that is determined by his/her skill and work environment. Manager A supervises two-thirds of the employees and manager B supervises the remaining third. The overall success rate for tasks in the firm is 0.95. Tasks supervised by Manager B have a success rate of 0.9.

- a. What is the probability that a randomly chosen task is performed successfully by an employee supervised by Manager B?
- b. Suppose a task is performed successfully. What is the probability that it was performed by an employee supervised by Manager B?
- c. Are the events “supervised by manager B” and “task performed successfully” independent? Explain.
- d. Based only on the information given, can you infer whether Manager A is better than Manager B? Explain your reasoning.
- e. Define a variable S_{it} , which equals one if employee i completes task t successfully and zero otherwise. You have 100 observations on S_{it} for 120 employees.
 - i. Propose an unbiased estimator for the success rate of employee i . Write down the variance of your estimator. State any assumptions you need.
 - ii. Consider the estimator

$$\tilde{\pi}_i = 0.5 * \frac{1}{100} \sum_{t=1}^{100} S_{it} + 0.5 * \frac{1}{12,000} \sum_{i=1}^{120} \sum_{t=1}^{100} S_{it}.$$

Derive the variance of $\tilde{\pi}_i$ and show that it is biased. State any assumptions you need.

- iii. Which estimator out of (i) and (ii) is more efficient (i.e., has smaller variance)? Which estimator do you prefer?

II. **Linear Regression** Consider the following linear regression model

$$\begin{aligned} y_i &= x_i' \beta + \varepsilon_i \\ E[x_i \varepsilon_i] &= 0 \\ E[\varepsilon_i^2 | x_i] &= (x_i' \gamma)^2 \end{aligned} \tag{1}$$

where x_i , β , and γ are $k \times 1$ vectors. Assume that $\{y_i, x_i\}$ is independent across i .

- a. Show that the OLS estimator of β is unbiased. State any additional assumptions you need.
- b. Derive the variance-covariance matrix of the OLS estimator of β . State any additional assumptions you need.
- c. Write down a consistent estimator for the variance-covariance matrix of the OLS estimator of β . State any additional assumptions you need.
- d. Show that the OLS estimator of β is consistent.
- e. Is the OLS estimator efficient? If not, propose an efficient estimator of β .
- f. Propose a consistent estimator for γ and prove that it is consistent. State any additional assumptions you need.

III. **Nonlinear Estimation** Consider the general extremum estimation problem, where

$$\theta_0 \equiv \arg \max_{\theta \in \Theta} Q(\theta),$$

where $\theta = (\theta_1, \theta_2, \dots, \theta_k)'$, i.e. $\dim(\theta) = k$.

- a. Let $Q_n(\theta)$ be the sample analogue of $Q(\theta)$. Define $\hat{\theta}$, an estimator of θ_0 , and give conditions for its consistency. Explain briefly how these conditions imply consistency of $\hat{\theta}$ for θ_0 .
- b. Consider the problem of estimating $y_i = T(x_i'\theta) + u_i$ using nonlinear least squares, where $T(\cdot)$ is a known function. State the population and the sample objective function, and define the estimand (the parameter to be estimated) and the estimator.
- c. Give primitive conditions for the assumptions you provided in (a) for consistency of the nonlinear least squares estimator. Make sure to specify the conditions that $T(\cdot)$ has to satisfy.
- d. Now derive an expression of the sampling error, $\sqrt{n}(\hat{\theta} - \theta_0)$, and give conditions for its asymptotic normality. Explain briefly how the conditions you propose imply the asymptotic normality of the sampling error.
- e. Suppose $T(z) = \Lambda(z) = e^z/(1 + e^z)$. Does $\Lambda(\cdot)$ satisfy the conditions required for consistency and asymptotic normality you specified above?
- f. Using the asymptotic distribution of the NLS estimator you provided in (d), give an estimator of the asymptotic variance, $Avar(\sqrt{n}(\hat{\theta} - \theta_0))$.
- g. Propose a Wald test, a likelihood ratio test and a Lagrange Multiplier test for the hypothesis that all elements of θ are equal to each other, i.e. $\theta_1 = \theta_2 = \dots = \theta_k$.

IV. Linear Panel Data Models.

- a. In this problem, we consider the linear fixed effects estimator.
 - i. For the linear model, where $y_{it} = x'_{it}\beta + \alpha_i + u_{it}$, define the linear fixed effects (FE) estimator and give conditions under which it is consistent and asymptotically normal. Show how the conditions are sufficient for the results.
 - ii. Explain intuitively what type of variation in the data is used to estimate β using FE.
 - iii. Show that for $T = 2$, the FE and first-difference estimators are identical.
 - iv. Assuming that u_{it} is homoskedastic and serially uncorrelated, write down the asymptotic variance of the FE estimator. Is the FE estimator asymptotically efficient?
- b. Consider the following panel of households in different counties in the United States that we observe over time. We observe $i = 1, \dots, n$ households in each county $c = 1, \dots, C$ over $t = 1, \dots, T$ years. Let $y_{ict} = x'_{ict}\beta + \lambda_i + \gamma_t + u_{ict}$, where $\dim(x_{ict}) = \dim(\beta) = k$. Let $x_{ic} = (x_{ic1}, x_{ic2}, \dots, x_{icT})$. $E[u_{ict}|x_{ic}, \lambda_i] = 0$, but $E[\lambda_i|x_{ic}] \neq 0$.
 - i. Propose a transformation of the above model that allows you to estimate β consistently. Define the estimator in question.
 - ii. Compare the variation in the data used in this problem to estimate β relative to your answer in (a.ii).
 - iii. Suppose $n \rightarrow \infty$, show the consistency of the estimator you propose in (b.i). Specify any condition required for the result.
 - iv. Now suppose $y_{ict} = x'_{ict}\beta + \lambda_i + \gamma_{ct} + u_{ict}$, how would your answer in (b.i) change?

Notation. θ_0 , Θ , y_i , x_i , $s(y_i, x_i; \theta)$ and $H(y_i, x_i; \theta)$ pertain to the objects defined in the 240B lecture notes.

Assumption ULLN 1 $\sup_{\theta \in \Theta} |\sum_{i=1}^n f(y_i, x_i; \theta)/n - E[f(y_i, x_i; \theta)]| \xrightarrow{P} 0$, if the following conditions hold,

- (i) (*i.i.d.*) $\{y_i, x_i\}_{i=1}^n$ is an i.i.d. sequence of random variables;
- (ii) (*Compactness*) Θ is compact;
- (iii) (*Continuity*) $f(y_i, x_i; \theta)$ is continuous in θ for all $(y_i, x_i)'$;
- (iv) (*Measurability*) $f(y_i, x_i; \theta)$ is measurable in $(y_i, x_i)'$ for all $\theta \in \Theta$;
- (v) (*Dominance*) There exists a dominating function $d(y_i, x_i)$ such that $|f(y_i, x_i; \theta)| \leq d(y_i, x_i)$ for all $\theta \in \Theta$ and $E[d(y_i, x_i)] < \infty$.

Assumption ULLN 2 $\sup_{\theta \in \Theta} |\sum_{i=1}^n f(y_i, x_i; \theta)/n - E[f(y_i, x_i; \theta)]| \xrightarrow{P} 0$, if the following conditions hold,

- (i) (*Law of Large Numbers*) $\{y_i, x_i\}$ is i.i.d., and $E[m(y_i, x_i; \theta)] < \infty$ for all $\theta \in \Theta$, which implies $\sum_{i=1}^n m(y_i, x_i; \theta)/n \xrightarrow{P} E[f(y_i, x_i; \theta)]$.
- (ii) (*Compactness of Θ*) Θ is in a compact subset of \mathbb{R}^k .
- (iii) (*Measurability in $(y_i, x_i)'$*) $f(y_i, x_i; \theta)$ is measurable in $(y_i, x_i)'$ for all $\theta \in \Theta$.
- (iv) (*Lipschitz Continuity*) For all $\theta, \theta' \in \Theta$, there exists $g(y_i, x_i)$, such that $|f(y_i, x_i; \theta) - f(y_i, x_i; \theta')| \leq g(y_i, x_i) \|\theta - \theta'\|$, for some norm $\|\cdot\|$, and $E[g(y_i, x_i)] < \infty$.

Formula for the score statistic

$$S \equiv \left(\frac{1}{\sqrt{n}} \sum_{i=1}^n s_i(\hat{\theta}_R) \right)' A_{nR}^{-1} C'_{nR} \left\{ \widehat{Avar} \left(C_{nR} A_{nR}^{-1} \sum_{i=1}^n s_i(\hat{\theta}_R) / \sqrt{n} \right) \right\}^{-1} C_{nR} A_{nR}^{-1} \left(\frac{1}{\sqrt{n}} \sum_{i=1}^n s_i(\hat{\theta}_R) \right)$$

GMM Expression for the Sampling Error

$$\sqrt{n}(\hat{\theta} - \theta_0) = - \left(\mathcal{H}'_0 W \frac{1}{n} \sum_{i=1}^n \frac{\partial h(y_i, w_i; \theta)}{\partial \theta} \Big|_{\theta=\theta^*} \right)^{-1} \mathcal{H}'_0 W \frac{1}{\sqrt{n}} \sum_{i=1}^n h(y_i, w_i; \theta_0) + o_p(1)$$

where

$$\mathcal{H}_0 = E \left[\frac{\partial h(y_i, w_i; \theta)}{\partial \theta'} \Big|_{\theta=\theta_0} \right]$$

Normal Distribution

Let $Z \sim N(0, 1)$, then its density is given by

$$\phi(z) = \frac{1}{\sqrt{2\pi}} \exp\left\{-\frac{1}{2}z^2\right\} \quad (1)$$

Its cdf is denoted by $\Phi(z)$.

Let $X \sim N(\mu, \sigma)$, then its density is given by

$$f(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left\{-\frac{1}{2}(x - \mu)^2/\sigma^2\right\} = \frac{1}{\sigma} \phi\left(\frac{x - \mu}{\sigma}\right) \quad (2)$$

and its cdf $F(x) = \Phi((x - \mu)/\sigma)$.